## Definition and Construction of an Equilateral Hyperbola (Part 1)



## I- Algebraic properties:

- 1°) **Odd** function: for any  $x \in \mathbb{R}^*$ , f(-x) = -f(x).
- 2°) Rate of growth *non constant* :  $T_{[f,(x_1,x_2)]} = \frac{f(x_2) f(x_1)}{x_2 x_1} = \frac{-A}{x_1 x_2}$
- 3°) Sign of T = Signe of (- A) on  $[0; +\infty[$  and on  $]-\infty; 0]$
- 4°) Variation Chart :

A > 0					A < 0					
x	<i>-∞</i> -1	0 1	$+\infty$	x	-∞	-1	0	1	$+\infty$	
Т	-	-		Т		+		+		
f		+ ~ ~	0(+)	f	0(+) -	-A	+∞ - ∘	• _A	<b>▼</b> 0 <sup>(-)</sup>	

**II-Geometric Properties** :

- 1°) The curve representing f is symmetrical through the Origin of axes. This curve is called an Equilateral Hyperbola because of its central Symmetry and because x and y vary in reverse directions. (The word <u>hyperbolic</u> means something exaggerated)
- 2°) The Hyperbola cuts the 1<sup>st</sup> bisector (y = x) in I  $(\sqrt{A}; \sqrt{A})$  if A > 0 or  $(\sqrt{-A}; -\sqrt{-A})$  if A < 0
- 3°) On I the Hyperbola is tangent to the line perpendicular to the bisector.
- 4°) The Hyperbola contains the point J(1;A) and its symmetrical point (-1;-A) through O
- 5°) If A > 0 the 1<sup>st</sup> bisector (y = x) is an axis of symmetry. If A < the 2<sup>nd</sup> bisector (y = -x) is an axis of symmetry.
- 6°) When |A| is very large compared to 1 (|A| >> 1), The Hyperbola is very wide and away from O. Inversely if |A| <<1 the Hyperbola is very narrow and close to 0.
- 7°) The Hyperbola contains absolutely no segment of a straight line.
- 8°) The Hyperbola has two *asymptotes* which are the axes of coordinates (Ox) et (Oy).



## Hyperbolas & Homographic Functions (Part 2)

**Homographic** functions are those defined by the type :  $f: x \mapsto y = \frac{ax+b}{cx+d}$  with  $c \neq 0$ 

That expression can take one or the other of the following forms :

$$(H_1) \quad y = \frac{A}{x}$$

$$(H_2) \quad y = \frac{A}{x} + H$$

$$(H_3) \quad y = \frac{A}{x - L}$$

$$(H_4) \quad y = \frac{A}{x - L} + H$$

$$(H_5) \quad y = \frac{ax + b}{cx + d}$$

- 1°) Transformation from (H<sub>1</sub>) to (H<sub>2</sub>) is a **Translation** defined by the vertical vector  $H_{j}$  (parallel to the (Oy) axis. (H<sub>2</sub>) intercepts (Oy) in y = H. ( $H = \ll Hight \gg ; L = \ll Length \gg$ )
- 2°) Transformation from (H<sub>1</sub>) to (H<sub>3</sub>) is a **Translation** defined by the horizontal vector L.  $\vec{i}$  (parallel to the (Ox) axis).
- 3°) Transformation from (H<sub>1</sub>) to (H<sub>4</sub>) is a **Translation** of vector  $\vec{V} = L.\vec{i} + H.\vec{j}$
- 4°) The Hyperbola (H<sub>4</sub>) has its center of symmetry in O'(L ;H). Let  $\mathbf{X} = \mathbf{x} - \mathbf{L}$  and  $\mathbf{Y} = \mathbf{y} - \mathbf{H}$  then  $\mathbf{Y} = \mathbf{A}/\mathbf{X}$  which means that (H<sub>4</sub>) is Symmetrical through O' Therefore (H<sub>4</sub>) is drawn in the system (O'X ; O'Y) just like (H<sub>1</sub>) in the system (*Ox*,*Oy*).
- 5°) To build the Hyperbola  $(H_5)$  one can choose between two methods :
  - a. Change  $(H_5)$  into  $(H_4)$  by breaking the fractions in simple elements (cf. examples).
  - b. Find the coordinates of the center with the formulas  $O'(L = \frac{-d}{c}; H = \frac{a}{c})$ then find the intersections with the two axes : (Oy) :  $(0; \frac{b}{d})$  and (Ox)  $(\frac{-b}{a}; 0)$ .

